

Matrices related to orthogonal hypercomplex polynomial systems

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Abstract

We show how special well known matrices, namely, the creation and shift matrices play an important role on a matrix representation of orthogonal systems of polynomials with a hypercomplex variable and values in a Clifford algebra.

Key words: hypercomplex polynomials, matrix representation, creation matrix, shift matrix

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1 Introduction

In [7] the author constructs orthogonal bases of polynomials in the space of square integrable functions that are in the kernel of a generalized Cauchy-Riemann operator in the unit ball of \mathbb{R}^{n+1} . The construction process relies on building blocks that do not belong, in general, to the kernel of the referred operator. By using results established in [3] for these building blocks, we generalize the algebraic approach developed in [1] and stress the role of the well-known *creation matrix* and *shift matrix* in this representation. We recall that the so-called creation matrix H and the shift matrix J are defined by

$$(H)_{il} = \begin{cases} i, & i = l + 1 \\ 0, & i \neq l + 1 \end{cases} \quad \text{and} \quad (J)_{il} = \begin{cases} 1, & i = l + 1 \\ 0, & i \neq l + 1, \end{cases}$$

$i, l = 0, \dots, m$, respectively. Although their simple structure, these matrices appear naturally in a matrix decomposition that represents polynomials in arbitrary dimension and in the framework of non-commutative algebras.

2 Basic concepts

Let $\{e_1, e_2, \dots, e_n\}$ be an orthonormal basis of the Euclidean vector space \mathbb{R}^n endowed with a non-commutative product according to the multiplication rules $e_k e_l + e_l e_k = -2\delta_{kl}$, $k, l = 1, \dots, n$, where δ_{kl} is the Kronecker symbol. The associative 2^n -dimensional Clifford algebra $\mathcal{C}\ell_{0,n}$ over \mathbb{R} is the set of numbers of the form $a = \sum_A a_A e_A$, $a_A \in \mathbb{R}$, with $A \subseteq \{1, \dots, n\}$, $e_A = e_{l_1} e_{l_2} \cdots e_{l_r}$, where $1 \leq l_1 < \dots < l_r \leq n$ and $e_\emptyset =: e_0 =: 1$. The vector space \mathbb{R}^{n+1} is embedded in $\mathcal{C}\ell_{0,n}$ by identifying $(x_0, x_1, \dots, x_n) \in \mathbb{R}^{n+1}$ with the so-called *paravectors* $x = x_0 + \underline{x} \in \mathcal{A}_n := \text{span}_{\mathbb{R}}\{1, e_1, \dots, e_n\} \subset \mathcal{C}\ell_{0,n}$, where $\underline{x} = x_1 e_1 + \dots + x_n e_n$ is called a *vector*. The conjugate \bar{x} and the norm $|x|$ of x are given by $\bar{x} = x_0 - \underline{x}$ and $|x| = (x\bar{x})^{1/2} = (\bar{x}x)^{1/2} = (\sum_{k=0}^n x_k^2)^{1/2}$, respectively. The generalized Cauchy-Riemann operator and its conjugate are given, respectively, by $\bar{\partial} := \frac{1}{2}(\partial_0 + \partial_{\underline{x}})$ and $\partial := \frac{1}{2}(\partial_0 - \partial_{\underline{x}})$, where $\partial_0 := \frac{\partial}{\partial x_0}$ and $\partial_{\underline{x}} := e_1 \frac{\partial}{\partial x_1} + \dots + e_n \frac{\partial}{\partial x_n}$.

We consider $\mathcal{C}\ell_{0,n}$ -valued functions defined in an open subset $\Omega \subseteq \mathbb{R}^{n+1} \cong \mathcal{A}_n$, i.e. functions of the form $f(z) = \sum_A f_A(z) e_A$ with $f_A(z)$ real valued. Continuously differentiable functions f that satisfy the equation $\bar{\partial}f = 0$ (resp. $f\bar{\partial} = 0$) are called (left) *monogenic* (resp. right monogenic) and constitute the analogue of the class of holomorphic functions in higher dimensions. For more details, see [2, 5].

Let f be a monogenic function that is hypercomplex-differentiable in some domain $\Omega \subset \mathbb{R}^{n+1}$ in the sense of [6]. Then f is real-differentiable and its (hypercomplex) derivative is given by $f' = \partial f$ in Ω .

3 Matrix representation of orthogonal Clifford algebra-valued polynomials

Branching techniques combined with Gelfand-Tsetlin bases approach yield to the monogenic polynomials

$$f_{k,\mu} = X_{n+1,k_n}^{(k-k_n)} X_{n,k_{n-1}}^{(k_n-k_{n-1})} \dots X_{3,k_2}^{(k_3-k_2)} \zeta^{k_2},$$

where $\zeta := x_1 - x_2 e_1 e_2$ and μ is an arbitrary sequence of integers $(k_{n+1}, k_n, \dots, k_3, k_2)$ such that $k = k_{n+1} \geq k_n \geq \dots \geq k_3 \geq k_2 \geq 0$. These polynomials form an orthogonal basis with respect to a suitable Clifford algebra valued inner product of the space of monogenic polynomials of degree k (see [7]). The building blocks $X_{n+1,j}^{(k-j)}$, $j = 0, \dots, k$, are, in general, non-monogenic polynomials and can be expressed as

$$X_{n+1,j}^{(k-j)}(x) = \sum_{s=0}^{k-j} \binom{k}{j+s} d_{j,s}(n) x_0^{k-j-s} \underline{x}^s, \quad x \in \mathcal{A}_n \tag{1}$$

where $d_{j,s}(n)$ are suitable real constants (cf. [3]). Given an arbitrary monogenic polynomial $P_j(\underline{x})$, in \mathbb{R}^n , of degree j , the system

$$\left\{ \tilde{X}_{n+1,j}^{(k)}(x) := X_{n+1,j}^{(k-j)}(x) P_j(\underline{x}), j = 0, \dots, k, x \in \mathcal{A}_n \right\}_{k \in \mathbb{N}} \quad (2)$$

is formed by monogenic polynomials where again (1) appear as building blocks.

The matrix representation of the building blocks relies on the so-called *shifted generalized Pascal matrix* $S_r(t) = e^{(H+rJ)t}$, $t \in \mathbb{R}, r \in \mathbb{N}_0$, that combines in a single expression both H and J matrices.

For this representation we restrict ourselves to vectors of polynomials up to a certain degree $m \in \mathbb{N}_0$. Therefore, for each $j = 0, \dots, k$, we consider the vectors $\xi(\underline{x}) = [1 \ \underline{x} \ \dots \ \underline{x}^m]^T$, $\mathbf{X}_j(x) = [X_{n+1,j}^{(0)}(x) \ X_{n+1,j}^{(1)}(x) \ \dots \ X_{n+1,j}^{(m)}(x)]^T$ and the diagonal matrix $\mathcal{D}_j = \text{diag}[d_{j,0}(n) \ d_{j,1}(n) \ \dots \ d_{j,m}(n)]$.

Theorem 3.1. *For each fixed j , the vector $\mathbf{X}_j(x)$ can be decomposed in the form*

$$\mathbf{X}_j(x) = S_j(x_0) \mathcal{D}_j \xi(\underline{x}). \quad (3)$$

Proof. For each fixed j and considering $l = k - j$, it holds

$$\partial_0 X_{n+1,j}^{(0)}(x) = 0 \quad \text{and} \quad \partial_0 X_{n+1,j}^{(l)}(x) = (l + j) X_{n+1,j}^{(l-1)}(x), \quad l > 0.$$

This property leads to the vector differential equation

$$\partial_0 \mathbf{X}_j(x) = (H + jJ) \mathbf{X}_j(x)$$

whose general solution is

$$\mathbf{X}_j(x) = e^{(H+jJ)x_0} \mathbf{X}_j(0, \underline{x}).$$

The result follows immediately noting that $X_{n+1,j}^{(l)}(0, \underline{x}) = d_{j,l}(n) \underline{x}^l$. □

The proposed decomposition (3) can be generalized for the whole orthogonal system (2) with the help of block matrices. The result highlights the role of the shift matrix J and its powers. Moreover, the generalized Pascal matrix $P(x_0) = S_0(x_0)$ comes into play as well (see [4]), connecting special simple matrices with real entries with hypercomplex entities.

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